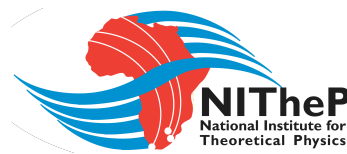


# Path integrals for classical Markov processes

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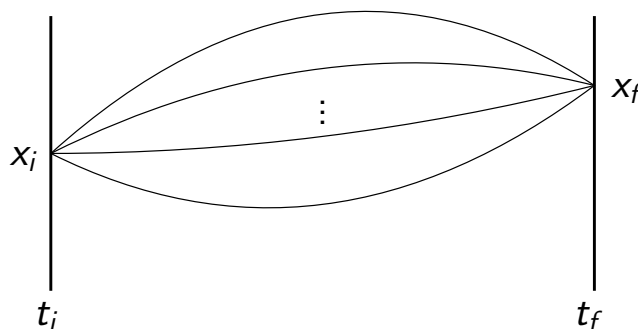
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Stellenbosch, South Africa

2014 Chris Engelbrecht Summer School on  
Non-Linear Phenomena in Field Theory  
Stellenbosch, South Africa  
21-31 January 2014



- Slides: [www.maths.qmul.ac.uk/~ht/talks.html](http://www.maths.qmul.ac.uk/~ht/talks.html)

## Quantum path integral



- Propagator:

$$K(x_f, t_f | x_i, t_i) = \langle x_f, t_f | x_i, t_i \rangle$$

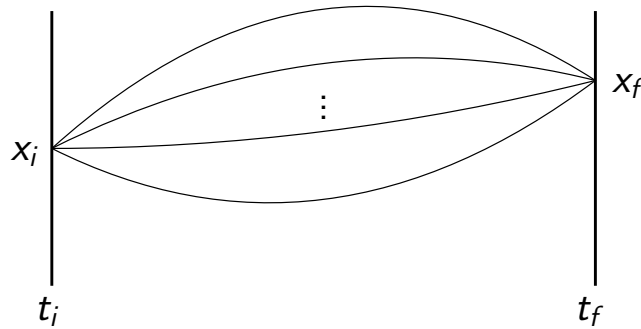
- Propagation:

$$\psi(x_f, t_f) = \int K(x_f, t_f | x_i, t_i) \psi(x_i, t_i) dx_i$$

- Path integral:

$$K(x_f, t_f | x_i, t_i) = \int_{x(t_i)}^{x(t_f)} \mathcal{D}[x] e^{iS[x]/\hbar} = \sum_{\text{all paths}} e^{iS[\text{path}]/\hbar}$$

# Classical path integral



- Propagator:

$$P(x_f, t_f | x_i, t_i) = \text{Prob}\{x(t_i) \rightarrow x(t_f)\}$$

- Propagation (Kolmogorov-Chapman equation):

$$P(x_f, t_f) = \int P(x_f, t_f | x_i, t_i) P(x_i, t_i) dx_i$$

- Path integral:

$$P(x_f, t_f | x_i, t_i) = \int_{x(t_i)}^{x(t_f)} \mathcal{D}[x] e^{-S[x]/\epsilon} = \sum_{\text{all paths}} e^{-S[\text{path}]/\epsilon}$$

## Comparison

### Quantum path integral

- $K$  quantum amplitude
- Interference possible
- Schrödinger equation:

$$i\hbar \frac{\partial}{\partial t} \psi(x, t) = H\psi(x, t)$$

- $H$  hermitian
- $\hbar \rightarrow 0$ : semi-classical limit

### Classical path integral

- $P$  classical probability
- No interference
- Fokker-Planck equation:

$$\frac{\partial}{\partial t} P(x, t) = LP(x, t)$$

- $L$  non-hermitian in general
- $\epsilon \rightarrow 0$ : low-noise limit

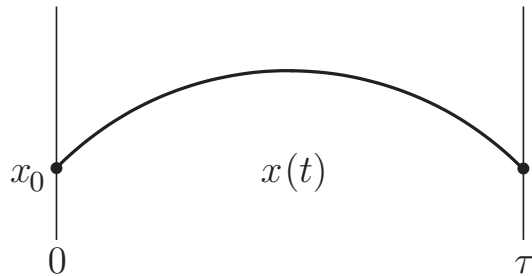
### Type of stochastic processes

- Continuous time Markov processes
- Stochastic differential equations

# Stochastic differential equations

- Deterministic dynamics (ODE):

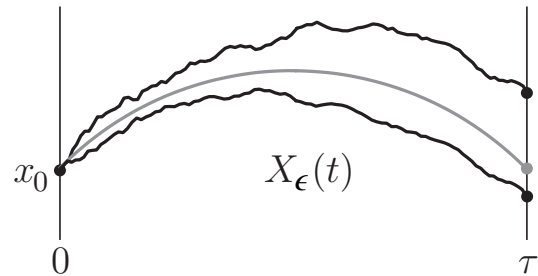
$$\dot{x}(t) = F(x)$$



$$x_{t+\Delta t} = x_t + F(x_t)\Delta t$$

- Perturbed dynamics (SDE):

$$\dot{X}_\epsilon(t) = F(X_\epsilon) + \underbrace{\sqrt{\epsilon}\xi(t)}_{\text{noise}}$$

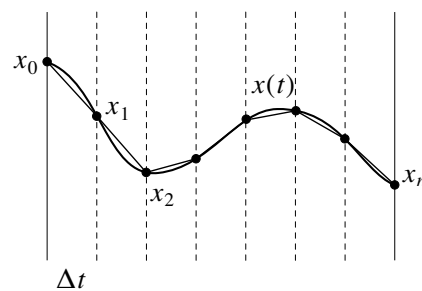
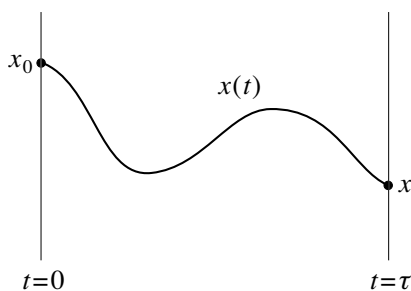


$$X_{t+\Delta t} = X_t + F(X_t)\Delta t + \sqrt{\epsilon}\Delta W_t$$

- Gaussian white noise:

$$\Delta W_t \sim \mathcal{N}(0, \Delta t)$$

## Path integral



- Time discretization:

$$\begin{aligned} P[x] &= \lim_{n \rightarrow \infty} P(x_1, x_2, \dots, x_n | x_0) \\ &= \lim_{n \rightarrow \infty} P(x_n | x_{n-1}) \cdots P(x_2 | x_1) P(x_1 | x_0) \end{aligned}$$

- Infinitesimal propagator:

$$P(x', t + \Delta t | x, t) = \frac{1}{\sqrt{2\pi\epsilon\Delta t}} \exp\left(-\frac{\Delta t}{2\epsilon} \left[\frac{x' - x}{\Delta t} - F(x)\right]^2\right)$$

- Path distribution:

$$P[x] = c e^{-S[x]/\epsilon}, \quad S[x] = \int_0^\tau L(\dot{x}, x) dt, \quad L = \frac{1}{2}[\dot{x} - F(x)]^2$$

# Dominant path approximation

- Low-noise approximation:

$$\begin{aligned}
 P(x_f, t_f | x_i, t_i) &= \int \mathcal{D}[x] e^{-S[x]/\epsilon} \\
 &\approx e^{-\min S[x]/\epsilon} \quad \epsilon \rightarrow 0 \\
 &= e^{-S[x^*]/\epsilon}
 \end{aligned}$$

- Final result:

$$\begin{aligned}
 P(x_f, t_f | x_i, t_i) &\approx e^{-V(x_f, t_f | x_i, t_i)/\epsilon} \\
 V(x_f, t_f | x_i, t_i) &= \min_{x(t): x(t_i)=x_i, x(t_f)=x_f} S[x]
 \end{aligned}$$

- Dominant path:

$$x^*(t) : \min S[x] \Rightarrow \delta S = 0$$

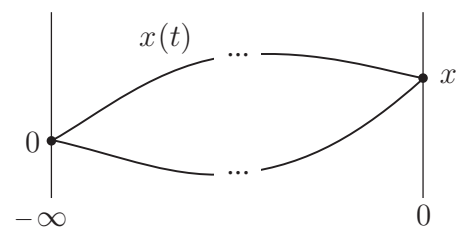
- Euler-Lagrange equation:

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{x}} - \frac{\partial L}{\partial x} = 0, \quad x(t_i) = x_i, x(t_f) = x_f$$

## Applications

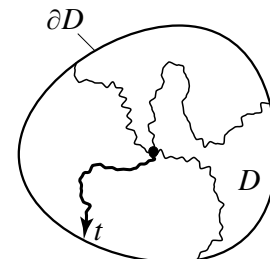
- Stationary distribution:

$$\begin{aligned}
 P(x) &\approx e^{-V(x)/\epsilon} \\
 V(x) &= \min_{x(t): x(-\infty)=0, x(0)=x} S[x]
 \end{aligned}$$



- Exit time:

$$\begin{aligned}
 \tau_\epsilon &\approx e^{V^*/\epsilon} \quad \text{in probability} \\
 V^* &= \min_{x \in \partial D} \min_{t \geq 0} V(x, t | x_0, 0)
 \end{aligned}$$



- Exit path = dominant path = instanton
- Exit location =  $x(\tau_\epsilon)$
- Semiclassical or WKB approximation

## Example: Ornstein-Uhlenbeck process

- SDE:

$$\dot{x}(t) = -\gamma x(t) + \sqrt{\epsilon} \xi(t)$$

- Stationary distribution:

$$P(x) \approx e^{-V(x)/\epsilon}, \quad V(x) = \min_{x(t): x(0)=x_0, x(\infty)=x} S[x]$$

- Euler-Lagrange equation:

$$\ddot{x} - \gamma^2 x = 0, \quad x(-\infty) = 0, x(0) = x$$

- Instanton solution:

$$x^*(t) = x e^{\gamma t}, \quad (\dot{x}^* = \gamma x^*)$$

- Solution:

$$V(x) = S[x^*] = \gamma x^2$$

- $P(x)$  Gaussian
- Instanton = time reverse of deterministic dynamics ( $\epsilon = 0$ )

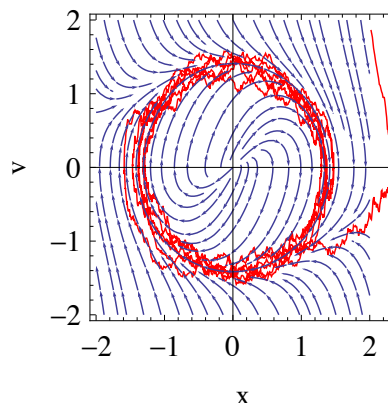
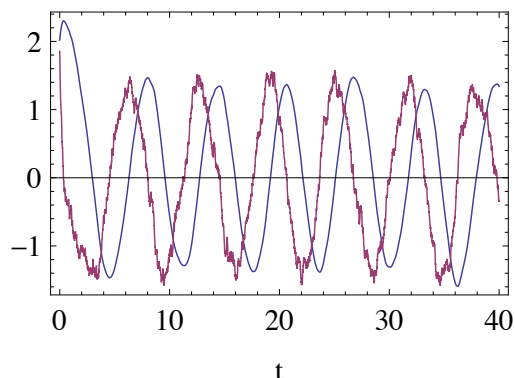
## Example: Noisy van der Pol oscillator

- SDE:

$$\begin{aligned} \dot{x} &= v \\ \dot{v} &= -x + v(\alpha - x^2 - v^2) + \sqrt{\epsilon} \xi(t) \end{aligned}$$

- Bifurcation:

- Stable fixed point:  $\alpha < 0$
- Stable limit cycle:  $\alpha > 0$

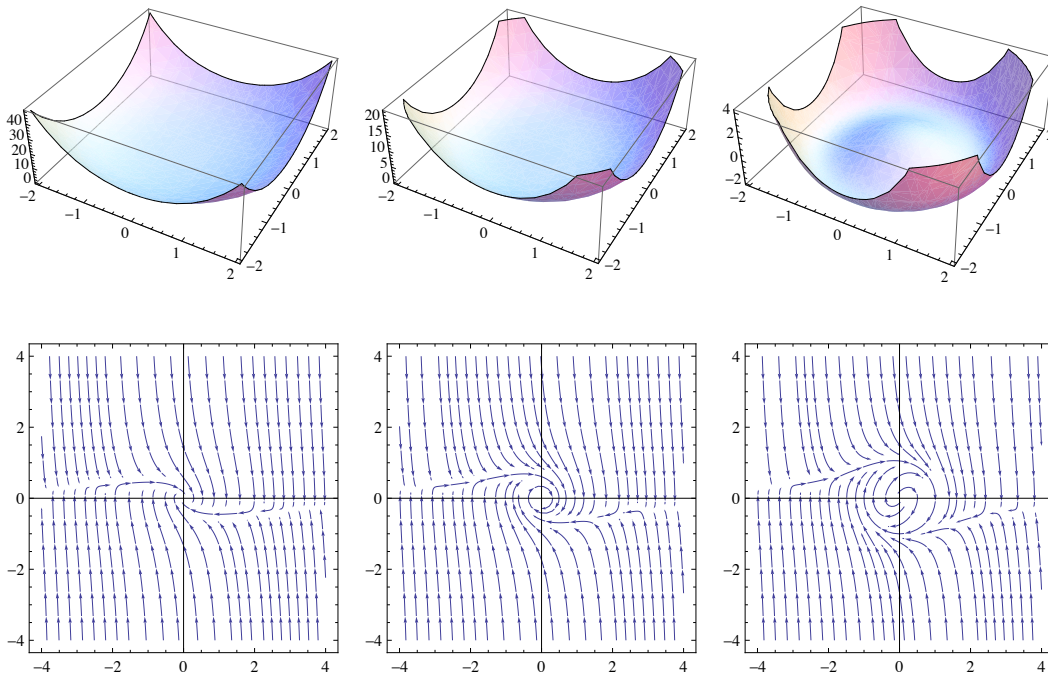


- Stationary distribution:  $P(r, \theta) \approx e^{-W(r)/\epsilon}$
- $W(r)$  given by Hamilton-Jacobi equation

# Noisy van der Pol oscillator (cont'd)

- Solution:

$$W(r) = -\alpha r^2 + \frac{r^4}{2}$$



## Gradient vs non-gradient

### Gradient system

$$\dot{x} = F(x) + \sqrt{\epsilon} \xi(t), \quad F(x) = -\nabla U(x)$$

- $V(x) = 2U(x)$
- Instanton = time-reversed deterministic dynamics
- Instanton equation:  $\dot{x}^* = \nabla U(x^*)$

### Non-gradient system

- $F \neq -\nabla U$
- Instanton  $\neq$  time-reversed deterministic dynamics
- Instanton dynamics:  $\dot{x}^* = F(x) + \nabla V(x)$

- Equilibrium vs nonequilibrium systems
- Detailed balance vs non-detailed balance

## Example: Linear, non-gradient system

$$\dot{x} = Bx + \sqrt{\epsilon} \xi, \quad B = \begin{pmatrix} -1 & -1 \\ 1 & -1 \end{pmatrix}$$

- Non-gradient:  $\dot{x} \neq -\nabla U$
- Stationary distribution:

$$P(x) \approx e^{-V(x,y)/\epsilon}$$

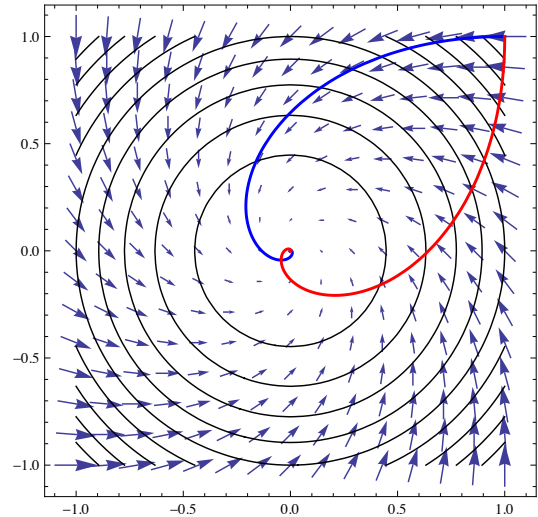
- Quasi-potential:

$$V(x, y) = x^2 + y^2$$

- Instanton:

$$\dot{x} = (-B_s + B_a)x = B^*x$$

$$B^* = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} = -B^T$$



## Summary

$$P(x_f, t_f | x_i, t_i) = \int_{x(t_i)}^{x(t_f)} \mathcal{D}[x] P[x], \quad P[x] = e^{-S[x]/\epsilon}$$

- Action:

$$S[x] = \int_{t_i}^{t_f} [\dot{x}_t - F(x_t)]^T A(x_t) [\dot{x}_t - F(x_t)] dt$$

- Dominant path approximation:

$$V(x_f, t_f | x_i, t_i) = \min_{x(t): x(t_i)=x_i, x(t_f)=x_f} S[x]$$

- Calculate all sorts of transition, escape probabilities
- Similar to semiclassical or WKB approximation
- Nonlinear equations difficult to solve in general
- Other noises: colored, Poisson, etc.

# Applications

## Physics

- Brownian motion
- Diffusion, transport
- Irreversible processes
- Noisy systems
- Biophysics

## Engineering

- Control, reliability
- Signal analysis, filtering
- Queueing

- Statistics, sampling
- Finance

## Further reading



H. Kleinert

Path Integrals in Quantum Mechanics, Statistics, Polymer Physics, and Financial Markets

World Scientific, 2005 [Chaps. 2, 4 and 20]



M. I. Freidlin, A. D. Wentzell

Random Perturbations of Dynamical Systems

Springer, New York, 1984, Chap. 4 [for the braves!]



R. Graham

Macroscopic potentials, bifurcations and noise in dissipative systems

F. Moss, P. V. E. McClintock (eds), Noise in Nonlinear Dynamical Systems, Cambridge University Press, 1989 [ask me a copy]



H. Touchette

The large deviation approach to statistical mechanics

Physics Reports 478, 1-69, 2009 [Sec. 6.1]





N. G. van Kampen

Stochastic Processes in Physics and Chemistry

North-Holland, 1992



B. Øksendal

Stochastic Differential Equations

Springer, 2000 [recommended]



K. Jacobs

Stochastic processes for Physicists: Understanding Noisy Systems

Cambridge, 2010 [recommended]



D. J. Higham

An algorithmic introduction to numerical simulation of stochastic differential equations

SIAM Review 43, 525-546, 2001

## Exercises

- 1 Re-do the calculation of page 6 to obtain the path distribution and the corresponding action.
- 2 Derive the expression of the propagator's quasi-potential  $V(x_f, t_f; x_i, t_i)$  for the Ornstein-Uhlenbeck process using the dominant path approximation. [Hint: Follow the stationary solution on page 9.] Check that the propagator verifies the time-dependent Fokker-Planck equation exactly.
- 3 Derive the stationary quasi-potential  $W(r)$  for the noisy van der Pol oscillator (page 10). Can you write down another dynamical system having the same quasi-potential?
- 4 Show for a gradient system that the instanton is the time-reverse of the deterministic path.
- 5 Derive the general result for the stationary quasi-potential shown on page 12.
- 6 What is the expression of the classical action  $S[x]$  using the Stratonovitch calculus convention? Is there any choice of calculus convention in quantum mechanics?