

Square roots of H-nonnegative matrices

Madelein van Straaten

Joint work with D.B. Janse van Rensburg; F. Theron; C. Trunk

North-West University

SAMS, 6 December 2022

Indefinite inner product

A function $[\cdot, \cdot]$ from $\mathbb{C}^n \times \mathbb{C}^n$ to $\mathbb{C}$ is called an *indefinite inner product* in $\mathbb{C}^n$ if the following hold for all $x, y, z \in \mathbb{C}^n$ and $\alpha, \beta \in \mathbb{C}$:

- (i) $[\alpha x + \beta y, z] = \alpha[x, z] + \beta[y, z]$ (linear in the first argument),
- (ii) $[x, y] = \overline{[y, x]}$ (anti-symmetric),
- (iii) and if $[x, y] = 0$ for all $y \in \mathbb{C}^n$, then $x = 0$ (nondegenerate).

Indefinite inner product

A function $[\cdot, \cdot]$ from $\mathbb{C}^n \times \mathbb{C}^n$ to $\mathbb{C}$ is called an *indefinite inner product* in $\mathbb{C}^n$ if the following hold for all $x, y, z \in \mathbb{C}^n$ and $\alpha, \beta \in \mathbb{C}$:

- (i) $[\alpha x + \beta y, z] = \alpha[x, z] + \beta[y, z]$ (linear in the first argument),
- (ii) $[x, y] = \overline{[y, x]}$ (anti-symmetric),
- (iii) and if $[x, y] = 0$ for all $y \in \mathbb{C}^n$, then $x = 0$ (nondegenerate).

It's known that $[x, y] = \langle Hx, y \rangle$, $x, y \in \mathbb{C}^n$, with H an $n \times n$ invertible Hermitian matrix.

Indefinite inner product

A function $[\cdot, \cdot]$ from $\mathbb{C}^n \times \mathbb{C}^n$ to $\mathbb{C}$ is called an *indefinite inner product* in $\mathbb{C}^n$ if the following hold for all $x, y, z \in \mathbb{C}^n$ and $\alpha, \beta \in \mathbb{C}$:

- (i) $[\alpha x + \beta y, z] = \alpha[x, z] + \beta[y, z]$ (linear in the first argument),
- (ii) $[x, y] = \overline{[y, x]}$ (anti-symmetric),
- (iii) and if $[x, y] = 0$ for all $y \in \mathbb{C}^n$, then $x = 0$ (nondegenerate).

It's known that $[x, y] = \langle Hx, y \rangle$, $x, y \in \mathbb{C}^n$, with H an $n \times n$ invertible Hermitian matrix.

A square complex matrix B is said to be *H-selfadjoint* if $[Bx, y] = [x, By]$ for all $x, y \in \mathbb{C}^n$,

Indefinite inner product

A function $[\cdot, \cdot]$ from $\mathbb{C}^n \times \mathbb{C}^n$ to $\mathbb{C}$ is called an *indefinite inner product* in $\mathbb{C}^n$ if the following hold for all $x, y, z \in \mathbb{C}^n$ and $\alpha, \beta \in \mathbb{C}$:

- (i) $[\alpha x + \beta y, z] = \alpha[x, z] + \beta[y, z]$ (linear in the first argument),
- (ii) $[x, y] = \overline{[y, x]}$ (anti-symmetric),
- (iii) and if $[x, y] = 0$ for all $y \in \mathbb{C}^n$, then $x = 0$ (nondegenerate).

It's known that $[x, y] = \langle Hx, y \rangle$, $x, y \in \mathbb{C}^n$, with H an $n \times n$ invertible Hermitian matrix.

A square complex matrix B is said to be *H-selfadjoint* if $[Bx, y] = [x, By]$ for all $x, y \in \mathbb{C}^n$, or equivalently, B is *H-selfadjoint* if

$$HB = B^*H.$$

Indefinite inner product

A function $[\cdot, \cdot]$ from $\mathbb{C}^n \times \mathbb{C}^n$ to $\mathbb{C}$ is called an *indefinite inner product* in $\mathbb{C}^n$ if the following hold for all $x, y, z \in \mathbb{C}^n$ and $\alpha, \beta \in \mathbb{C}$:

- (i) $[\alpha x + \beta y, z] = \alpha[x, z] + \beta[y, z]$ (linear in the first argument),
- (ii) $[x, y] = \overline{[y, x]}$ (anti-symmetric),
- (iii) and if $[x, y] = 0$ for all $y \in \mathbb{C}^n$, then $x = 0$ (nondegenerate).

It's known that $[x, y] = \langle Hx, y \rangle$, $x, y \in \mathbb{C}^n$, with H an $n \times n$ invertible Hermitian matrix.

A square complex matrix B is said to be *H-selfadjoint* if $[Bx, y] = [x, By]$ for all $x, y \in \mathbb{C}^n$, or equivalently, B is *H-selfadjoint* if

$$HB = B^*H.$$

Furthermore, if B is an *H-selfadjoint* matrix, then $\sigma(B)$ is symmetric relative to the real axis.

Notation

Let the *Jordan normal form* of a square matrix B be given by $S^{-1}BS = J_{n_1}(\lambda_1) \oplus \cdots \oplus J_{n_s}(\lambda_s)$, where

$$J_{n_i}(\lambda_i) = \begin{bmatrix} \lambda_i & 1 & & \\ & \ddots & \ddots & \\ & & \ddots & 1 \\ & & & \lambda_i \end{bmatrix},$$

for $\lambda_i \in \sigma(B)$.

Notation

Let the *Jordan normal form* of a square matrix B be given by $S^{-1}BS = J_{n_1}(\lambda_1) \oplus \cdots \oplus J_{n_s}(\lambda_s)$, where

$$J_{n_i}(\lambda_i) = \begin{bmatrix} \lambda_i & 1 & & \\ & \ddots & \ddots & \\ & & \ddots & 1 \\ & & & \lambda_i \end{bmatrix},$$

for $\lambda_i \in \sigma(B)$. Let Q_n denote the $n \times n$ *sip matrix*:

$$Q_n = \begin{bmatrix} & & 1 \\ & \ddots & \\ 1 & & \end{bmatrix}.$$

Canonical form of (A, H) where A is H -selfadjoint

Theorem 1

Let $A \in \mathbb{C}^{n \times n}$ be an H -selfadjoint matrix. Then there exists an invertible matrix S over $\mathbb{C}$ such that $S^{-1}AS$ and S^*HS have the form

$$S^{-1}AS = J_{k_1}(\lambda_1) \oplus \cdots \oplus J_{k_\alpha}(\lambda_\alpha) \oplus [J_{k_{\alpha+1}}(\lambda_{\alpha+1}) \oplus J_{k_{\alpha+1}}(\bar{\lambda}_{\alpha+1})] \oplus \cdots \oplus [J_{k_\beta}(\lambda_\beta) \oplus J_{k_\beta}(\bar{\lambda}_\beta)] \quad (1)$$

where $\lambda_1, \dots, \lambda_\alpha$ are real and $\lambda_{\alpha+1}, \dots, \lambda_\beta$ are nonreal with positive imaginary parts; and

$$S^*HS = \varepsilon_1 Q_{k_1} \oplus \cdots \oplus \varepsilon_\alpha Q_{k_\alpha} \oplus Q_{2k_{\alpha+1}} \oplus \cdots \oplus Q_{2k_\beta} \quad (2)$$

where $\varepsilon_1, \dots, \varepsilon_\alpha$ are ± 1 . The canonical form given by (1) and (2) is uniquely determined by the pair (A, H) , up to a permutation of diagonal blocks.

Canonical form of (A, H) where A is H -selfadjoint

Theorem 1

Let $A \in \mathbb{C}^{n \times n}$ be an H -selfadjoint matrix. Then there exists an invertible matrix S over $\mathbb{C}$ such that $S^{-1}AS$ and S^*HS have the form

$$S^{-1}AS = J_{k_1}(\lambda_1) \oplus \cdots \oplus J_{k_\alpha}(\lambda_\alpha) \oplus [J_{k_{\alpha+1}}(\lambda_{\alpha+1}) \oplus J_{k_{\alpha+1}}(\bar{\lambda}_{\alpha+1})] \oplus \cdots \oplus [J_{k_\beta}(\lambda_\beta) \oplus J_{k_\beta}(\bar{\lambda}_\beta)] \quad (1)$$

where $\lambda_1, \dots, \lambda_\alpha$ are real and $\lambda_{\alpha+1}, \dots, \lambda_\beta$ are nonreal with positive imaginary parts; and

$$S^*HS = \varepsilon_1 Q_{k_1} \oplus \cdots \oplus \varepsilon_\alpha Q_{k_\alpha} \oplus Q_{2k_{\alpha+1}} \oplus \cdots \oplus Q_{2k_\beta} \quad (2)$$

where $\varepsilon_1, \dots, \varepsilon_\alpha$ are ± 1 . The canonical form given by (1) and (2) is uniquely determined by the pair (A, H) , up to a permutation of diagonal blocks.

Sign characteristic and Segre characteristic

Definition 2

Let B be an $n \times n$ complex H -selfadjoint matrix with a single real eigenvalue λ and geometric multiplicity of one. We say B has a *positive sign characteristic* (with respect to H) if (B, H) has canonical form $(J_n(\lambda), Q_n)$ and a *negative sign characteristic* (with respect to H) if (B, H) has canonical form $(J_n(\lambda), -Q_n)$.

Sign characteristic and Segre characteristic

Definition 2

Let B be an $n \times n$ complex H -selfadjoint matrix with a single real eigenvalue λ and geometric multiplicity of one. We say B has a *positive sign characteristic* (with respect to H) if (B, H) has canonical form $(J_n(\lambda), Q_n)$ and a *negative sign characteristic* (with respect to H) if (B, H) has canonical form $(J_n(\lambda), -Q_n)$.

Definition 3

Let B be a square nilpotent matrix with Jordan form $J = \bigoplus_{i=1}^r J_{n_i}(0)$ and assume that $n_1 \geq n_2 \geq n_3 \geq \dots \geq n_r > 0$, where n_i represents the length of a Jordan chain. The *Segre characteristic* of B is defined as

$$(n_1, n_2, n_3, \dots, n_r).$$

Example 1

Let the following matrices be given

$$B = J_2(0) \oplus J_2(0) \oplus J_1(0) \oplus J_1(0) = \begin{bmatrix} 0 & 1 & & & \\ 0 & 0 & & & \\ & & 0 & 1 & \\ & & 0 & 0 & \\ & & & & 0 \\ & & & & & 0 \end{bmatrix};$$

$$H = Q_2 \oplus Q_2 \oplus -Q_1 \oplus Q_1 = \begin{bmatrix} 0 & 1 & & & \\ 1 & 0 & & & \\ & & 0 & 1 & \\ & & 1 & 0 & \\ & & & & -1 \\ & & & & & 1 \end{bmatrix}.$$

The matrix B is H -nonnegative and has Segre characteristic $(2, 2, 1, 1)$.

H -selfadjoint square roots of H -selfadjoint matrices

Theorem 4 ([van der Mee, Ran, Rodman, 1999])

Let B be an H -selfadjoint matrix. Then there exists an H -selfadjoint matrix A such that $A^2 = B$ if and only if the canonical form of (B, H) has the following properties:

- (i) the Jordan blocks corresponding to the negative eigenvalues exist in pairs and the two Jordan blocks in each pair have opposite sign characteristic;*
- (ii) the Jordan blocks corresponding to the zero eigenvalue can be written as $J^{(1)} \oplus J^{(2)} \oplus J^{(3)}$, where $J^{(1)}$ is a direct sum of pairs $J_{p_i}(0) \oplus J_{p_i}(0)$, $J^{(2)}$ is a direct sum of pairs $J_{p_i}(0) \oplus J_{p_i-1}(0)$ and $J^{(3)}$ is a direct sum of 1×1 blocks and where the blocks in each pair in $J^{(1)}$ have opposite sign characteristic and those in each pair in $J^{(2)}$ have the same sign characteristic.*

The problem

A square complex matrix B is called *H-nonnegative* if $[Bx, x] \geq 0$ for all $x \in \mathbb{C}^n$.

The problem

A square complex matrix B is called *H -nonnegative* if $[Bx, x] \geq 0$ for all $x \in \mathbb{C}^n$.

Let B be an H -nonnegative matrix.

- Finding necessary and sufficient conditions for the existence of a square root for B .
- Finding a description of all possible square roots of nilpotent H -nonnegative matrices.
- Extending the results to finding H -selfadjoint and H -nonnegative square roots of B .

Characteristics of H -nonnegative matrices

Theorem 5 ([Gohberg, Lancaster, Rodman, 2005])

A matrix B is H -nonnegative if and only if the following hold:

- (i) B is H -selfadjoint;
- (ii) B has a real spectrum;
- (iii) the canonical form of the pair (B, H) is $(S^{-1}BS, S^*HS)$ which is given by

$$S^{-1}BS = \bigoplus_{i=1}^q J_1(\lambda_i) \oplus \bigoplus_{i=1}^{r-q} J_1(\lambda_{q+i}) \oplus \bigoplus_{i=1}^s J_1(0) \oplus \bigoplus_{i=1}^t J_2(0),$$

$$S^*HS = \bigoplus_{i=1}^q Q_1 \oplus \bigoplus_{i=1}^{r-q} (-Q_1) \oplus \bigoplus_{i=1}^s \varepsilon_i Q_1 \oplus \bigoplus_{i=1}^t Q_2,$$

where $\lambda_1, \dots, \lambda_q > 0$, $\lambda_{q+1}, \dots, \lambda_r < 0$, and $\varepsilon_i = \pm 1$.

Conditions for existence of a square root

Theorem 6 (See e.g. [Cross and Lancaster, 1974])

For any nilpotent matrix B there exists a square root A if and only if there exists a reordering $n_1, n_2, \dots, n_p$ for some p , of the Segre characteristic of B such that the difference $n_{2j} - n_{2j-1}$ of each pair is equal to zero or one for all $j = 1, \dots, \frac{p}{2}$.

Conditions on H -nonnegative matrix

Write any H -nonnegative matrix B in Jordan normal form as $B = B_- \oplus B_0 \oplus B_+$, where B_- has a negative spectrum, B_+ a positive spectrum, and B_0 has only zero in the spectrum.

Conditions on H -nonnegative matrix

Write any H -nonnegative matrix B in Jordan normal form as $B = B_- \oplus B_0 \oplus B_+$, where B_- has a negative spectrum, B_+ a positive spectrum, and B_0 has only zero in the spectrum.

Theorem 7

Let B_0 be a nilpotent H -nonnegative matrix. Then the following hold:

- (i) If B_0 has an even number of Jordan chains of length two, then B_0 has a square root.*
- (ii) If B_0 has an odd number of Jordan chains of length two, then B_0 has a square root if and only if B_0 has at least one Jordan chain of length one.*

Example

Example 2

Let B be H -nonnegative, with $B = J_2(0) \oplus J_2(0) \oplus J_1(0) \oplus J_1(0)$ and $H = Q_2 \oplus Q_2 \oplus -Q_1 \oplus Q_1$. Then the Segre characteristic of B is $(2, 2, 1, 1)$. Now there exists three different reorderings or pairings which can each deliver a square root:

- $(2, 2), (1, 1)$
- $(2, 2), (1, 0), (1, 0)$
- $(2, 1), (2, 1)$

Descriptions of square roots

Theorem 8

Let B_0 be a nilpotent H -nonnegative matrix in canonical form. That is, $B_0 = \bigoplus_{i=1}^t J_2(0) \oplus \bigoplus_{i=1}^s J_1(0)$. Then the square roots of blocks with all possible Segre characteristic are given as:

- 1 The square root of $J_1(0) = [0]$, which is associated with the pair $(1, 0)$, is equal to $[0]$;
- 2 The square root of $J_1(0) \oplus J_1(0)$, which is associated with the pair $(1, 1)$, is

$$\begin{bmatrix} \alpha & \frac{-\alpha^2}{\beta} \\ \beta & -\alpha \end{bmatrix}, \text{ for any complex numbers } \alpha, \beta \text{ with } \beta \neq 0, \text{ or } \begin{bmatrix} 0 & \alpha \\ 0 & 0 \end{bmatrix} \quad (3)$$

for any nonzero complex number α ;

Descriptions of square roots

Theorem 8 continued

- 3 The square root of $J_2(0) \oplus J_1(0)$, which is associated with the pair $(2, 1)$, is

$$\begin{bmatrix} 0 & \alpha & \beta \\ 0 & 0 & 0 \\ 0 & \frac{1}{\beta} & 0 \end{bmatrix}, \text{ for complex numbers } \alpha \text{ and } \beta \neq 0; \quad (4)$$

- 4 The square root of $J_2(0) \oplus J_2(0)$, which is associated with $(2, 2)$, is

$$\begin{bmatrix} -\alpha_3 & -\alpha_4 & \frac{-\alpha_3^2}{\alpha_1} & \beta \\ 0 & -\alpha_3 & 0 & \frac{-\alpha_3^2}{\alpha_1} \\ \alpha_1 & \alpha_2 & \alpha_3 & \alpha_4 \\ 0 & \alpha_1 & 0 & \alpha_3 \end{bmatrix}, \text{ or } \begin{bmatrix} 0 & \gamma_1 & \gamma_2 & \gamma_3 \\ 0 & 0 & 0 & \gamma_2 \\ 0 & \frac{1}{\gamma_2} & 0 & -\gamma_1 \\ 0 & 0 & 0 & 0 \end{bmatrix}, \quad (5)$$

where α_1, γ_2 is nonzero, and $\beta = \frac{1}{\alpha_1^2}(\alpha_1 + \alpha_3^2\alpha_2 - 2\alpha_1\alpha_3\alpha_4)$.

Example

Let B and H be given by

$$B = \left[\begin{array}{cc|c} 0 & 1 & 0 \\ 0 & 0 & 0 \\ \hline 0 & 0 & 0 \end{array} \right], \quad H = Q_2 \oplus -Q_1 = \left[\begin{array}{cc|c} 0 & 1 & 0 \\ 1 & 0 & 0 \\ \hline 0 & 0 & -1 \end{array} \right].$$

Then B is H -nonnegative. The matrix

$$A = \begin{bmatrix} 0 & 1 & i \\ 0 & 0 & 0 \\ 0 & -i & 0 \end{bmatrix}$$

is a square root of B , but is not H -selfadjoint (i.e. $HA \neq A^*H$).

Example

Let B and H be given by

$$B = \left[\begin{array}{cc|c} 0 & 1 & 0 \\ 0 & 0 & 0 \\ \hline 0 & 0 & 0 \end{array} \right], \quad H = Q_2 \oplus -Q_1 = \left[\begin{array}{cc|c} 0 & 1 & 0 \\ 1 & 0 & 0 \\ \hline 0 & 0 & -1 \end{array} \right].$$

Then B is H -nonnegative. The matrix

$$A = \begin{bmatrix} 0 & 1 & i \\ 0 & 0 & 0 \\ 0 & -i & 0 \end{bmatrix}$$

is a square root of B , but is not H -selfadjoint (i.e. $HA \neq A^*H$). The matrix A is however H' -selfadjoint where

$$H' = Q_2 \oplus Q_1 = \left[\begin{array}{cc|c} 0 & 1 & 0 \\ 1 & 0 & 0 \\ \hline 0 & 0 & 1 \end{array} \right].$$

Existence of H -selfadjoint square roots

Recall that for an H -nonnegative matrix we denote by

- s the number of Jordan blocks at zero of size one,
- t the number of Jordan blocks at zero of size two.

For the following we denote by s_+ (s_-) the number of positive (resp. negative) entries in the vector $(\varepsilon_1, \dots, \varepsilon_s)$, hence we have

$$s = s_- + s_+.$$

Existence of H -selfadjoint square roots

Recall that for an H -nonnegative matrix we denote by

- s the number of Jordan blocks at zero of size one,
- t the number of Jordan blocks at zero of size two.

For the following we denote by s_+ (s_-) the number of positive (resp. negative) entries in the vector $(\varepsilon_1, \dots, \varepsilon_s)$, hence we have

$$s = s_- + s_+.$$

Theorem 9 ([Janse van Rensburg, vS, Theron, Trunk])

An H -nonnegative matrix B in $\mathbb{C}^n$ has an H -selfadjoint square root if and only if B satisfies the following conditions.

- 1 $\sigma(B) \subset [0, \infty)$;
- 2 $s_+ \geq t$;

Existence of H -nonnegative square roots

Theorem 10 ([Janse van Rensburg, vS, Theron, Trunk])

An H -nonnegative matrix B in $\mathbb{C}^{n \times n}$ has an H -nonnegative square root if and only if the following properties hold:

- (i) $\sigma(B) \subset [0, \infty)$;
- (ii) B has no Jordan blocks of size two at the eigenvalue zero, that is, $t = 0$.

References



Y. Bolshakov, C.V.M. van der Mee, A.C.M. Ran, B. Reichstein, L. Rodman (1997)
Polar decompositions in finite dimensional indefinite scalar product spaces: General Theory
Linear algebra and its applications: 216, 91–141.



G.W. Cross and P. Lancaster (1974)
Square roots of complex matrices
Linear and Multilinear Algebra, 1, 289–293.



I. Gohberg, P. Lancaster, L. Rodman (2005)
Indefinite Linear Algebra and Applications
Birkhäuser Verlag, Basel.



D.B. Janse van Rensburg, M. van Straaten, F. Theron, C. Trunk (2021)
Square roots of H -nonnegative matrices
Linear Algebra and its Applications, 621, 29–49.



C.V.M. van der Mee, A.C.M. Ran, and L. Rodman (1999)
Stability of self-adjoint square roots and polar decompositions in indefinite scalar product spaces
Linear Algebra and its Applications, 302-303, 77–104.



NWU®

Thank you.

This work is based on research supported in part by the DSI-NRF Centre of Excellence in Mathematical and Statistical Sciences (CoE-MaSS).