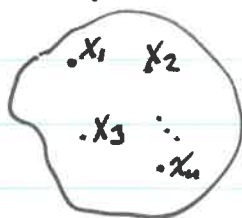


Chapter 2: Markov chain Monte Carlo

2.1 Introduction

MC



$$P(x_1, x_2, \dots, x_n) = P(x_1) P(x_2) \dots P(x_n)$$

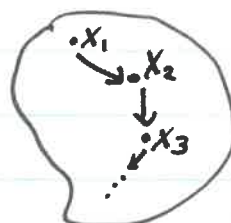
Independent samples

$$S_L = \{x_i\}_{i=1}^L$$

$$\text{Histogram}(S_L) \approx p$$

Sample p directly

MCMC



$$P(x_1, x_2, \dots, x_n) = P(x_1) P(x_2 | x_1) \dots P(x_n | x_{n-1})$$

Markov samples: $P(x \rightarrow x') = P(x' | x)$

$$S_L = \{x_i\}_{i=1}^L \quad \text{'trajectory'}$$

$$\text{Histogram}(S_L) \approx p$$

Choose transition probabilities by $P(x \rightarrow x')$ to sample p

Grimmett
Sturges
Chap 6

2.2. Markov chains

Def: $(X_i)_{i=1}^n$ is a discrete-time Markov chain (MC) if

$$P(X_n = x_n \mid X_1 = x_1, X_2 = x_2, \dots, X_{n-1} = x_{n-1}) = \underbrace{P(X_n = x_n \mid X_{n-1} = x_{n-1})}_{\text{transition probability}}$$

In all $n \geq 1$ and all x_1, x_2, \dots, x_n .
all sequences *all values*

$$\Rightarrow P(x_1, x_2, \dots, x_n) = P(x_1) P(x_2 | x_1) \dots P(x_n | x_{n-1})$$

$$x_1 \rightarrow x_2 \rightarrow \dots \rightarrow x_n$$

Assumptions/restrictions:

- $x_i \in \mathcal{X}$ discrete/countable state space

- $P(X_n = b \mid X_{n-1} = a)$ doesn't depend on n

time

$$\Rightarrow P(X_n = b \mid X_{n-1} = a) = P(X_2 = b \mid X_1 = a) \quad \forall n$$

Time-invariant, time-independent, homogeneous

Transition matrix

$$P(X_n = j | X_{n-1} = i) = P(i \rightarrow j) = \pi_{ij} \quad \text{or} \quad P_{ij}$$

• $|X| \times |X|$ matrix

• $0 \leq \pi_{ij} \leq 1 \quad \forall i, j$

• $\sum_j \pi_{ij} = 1 \quad \forall i$

} Stochastic matrix

$$\Pi = (\pi_{ij}) = \begin{pmatrix} \pi_{11} & \pi_{12} & \pi_{13} & \dots \\ \pi_{21} & \pi_{22} & \pi_{23} & \dots \\ \vdots & & \ddots & \end{pmatrix} \quad \text{row sum} = 1$$

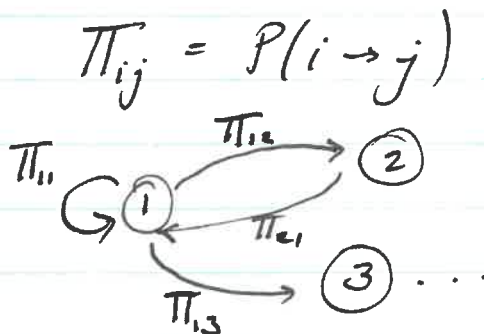
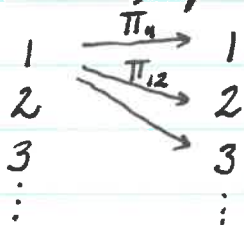
row column

Rem: Different convention (used in physics)

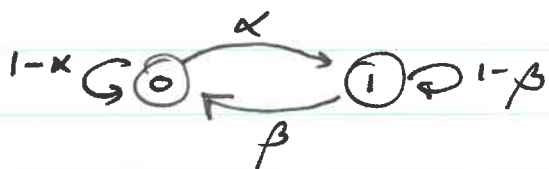
$$P(i \rightarrow j) = \tilde{\pi}_{ji} \quad \sum_j \tilde{\pi}_{ji} = 1 \quad \forall i$$

$$\tilde{\Pi} = \Pi^T$$

• Graphical representation: $\pi_{ij} = P(i \rightarrow j)$

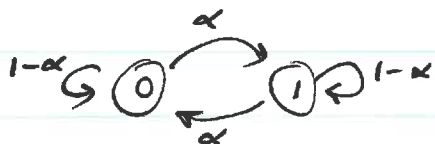


• Example: 2-state MC



$$\Pi = \begin{pmatrix} 1-\alpha & \alpha \\ \beta & 1-\beta \end{pmatrix} \begin{array}{l} \rightarrow \sum \dots = 1 \\ \rightarrow \sum \dots = 1 \end{array}$$

• $\beta = \alpha$: Symmetric MC



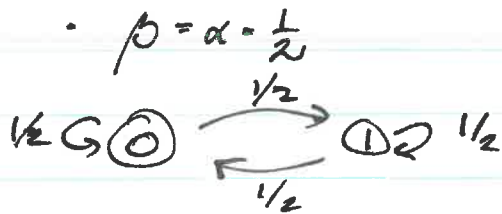
$$\Pi = \begin{pmatrix} 1-\alpha & \alpha \\ \alpha & 1-\alpha \end{pmatrix}$$

• $\alpha \approx 0$: 000... 1111... 0010...

• $\alpha \approx 1$: 0101... 001101...

persistence
long sequences
of 0's, 1's

anti-persistent
alternating bits



$$\Pi = \begin{pmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{pmatrix}$$

Coin tossing. No correlation

Rem: Independent MC if Π_{ij} doesn't depend on i :
 $P(i \rightarrow j) = P(j)$ *all rows the same*

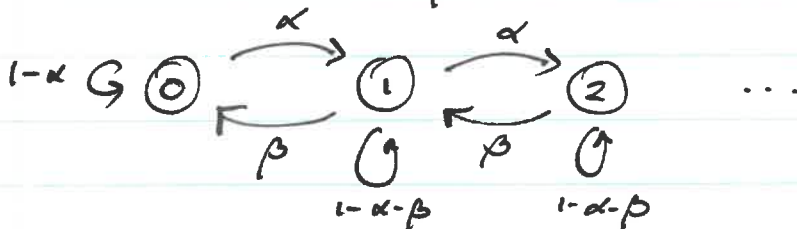
$$\Rightarrow P(X_1, X_2, \dots, X_n) = P(X_1) P(X_2) \dots P(X_n) \quad \text{iid model}$$

• Example: Population model / birth-death process

• $X_i \in \{0, 1, 2, \dots\}$

• $P(i \rightarrow i+1) = \alpha$ births

• $P(i \rightarrow i-1) = \beta$ deaths



2.3 Probability propagation

$$X_1 \rightarrow X_2 \rightarrow \dots \rightarrow X_n$$

$P(X_1)$ $P(X_n)?$

$$P(X_1, X_2) = P(X_1) P(X_2 | X_1)$$

$$\begin{aligned} \Rightarrow P(X_2 = j) &= \sum_i P(X_1 = i, X_2 = j) \\ &= \sum_i P(X_1 = i) P(X_2 = j | X_1 = i) \end{aligned}$$

$$\begin{aligned} \Rightarrow P(X_{n+1} = j) &= \sum_i P(X_n = i) P(X_{n+1} = j | X_n = i) \\ &= \sum_i P(X_n = i) \Pi_{ij} \end{aligned}$$

Matrix notation:

$$\bar{P}_n \quad (\bar{p}_n)_i = \bar{P}_n(i) = P(X_n = i) \quad \sum_i \bar{p}_n(i) = 1$$

$$\Pi \quad (\Pi)_{ij} = P(X_{n+1} = j | X_n = i) \quad \sum_j \Pi_{ij} = 1$$

Propagation formula:

$$\bar{P}_{n+1} = \bar{P}_n \Pi$$

Chapman-Kolmogorov
Equation

row vector row matrix

$$(p_{n+1}(1) \ p_{n+1}(2) \ \dots) = (p_n(1) \ p_n(2) \ \dots) \begin{pmatrix} \Pi \\ \end{pmatrix}$$

$$\bar{P}_2 = \bar{P}_1 \Pi$$

$$\bar{P}_3 = \bar{P}_2 \Pi = \bar{P}_1 \Pi \Pi = \bar{P}_1 \Pi^2$$

⋮

$$\bar{P}_n = \bar{P}_{n-1} \Pi = \bar{P}_1 \Pi^{n-1}$$

n-1 step transition prob.

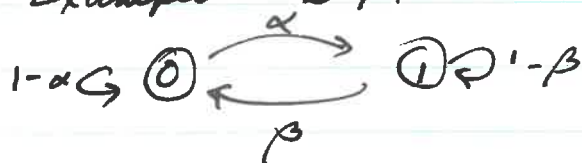
$$P(X_n = j) = \sum_i P(X_1 = i) (\Pi^n)_{ij}$$

$$= \sum_i P(X_1 = i) \underbrace{P(X_n = j | X_1 = i)}_{n-1 \text{ steps}}$$

$$X_1 \xrightarrow{\Pi} X_2 \xrightarrow{\Pi} \dots \xrightarrow{\Pi} X_n$$

$$P(X_1) \qquad \qquad \qquad P(X_n)$$

Example: 2-state MC



$$\Pi = \begin{pmatrix} 1-\alpha & \alpha \\ \beta & 1-\beta \end{pmatrix}$$

$$(p_{n+1}(0) \ p_{n+1}(1)) = (p_n(0) \ p_n(1)) \begin{pmatrix} 1-\alpha & \alpha \\ \beta & 1-\beta \end{pmatrix}$$

$$\rightarrow \begin{aligned} p_{n+1}(0) &= (1-\alpha) p_n(0) + \beta p_n(1) \\ p_{n+1}(1) &= \alpha p_n(0) + (1-\beta) p_n(1) \end{aligned}$$

Rem: Column vector convention

$$\begin{pmatrix} | \\ P_{n+1} \\ | \end{pmatrix} = \begin{pmatrix} \tilde{\Pi} \\ \bar{P}_n \end{pmatrix} \quad \text{vs} \quad (P_{n+1}) = (P_n) \begin{pmatrix} \Pi \end{pmatrix}$$

2.4. Ergodic Markov chains

• Stationary distribution:

$$P^* = P^* \Pi$$

• Fixed point of Π : $P_1 = P^* \rightarrow P_2 = P_1 \Pi = P^* \Pi = P^*$

$$\Rightarrow P_n = P^* \quad \forall n$$

• Eigenvector of Π with eigenvalue 1 (left eigenvect)

• Π can have many stationary dist.

• Limiting distribution:

$$P_\infty = \lim_{n \rightarrow \infty} P_n = \lim_{n \rightarrow \infty} P_1 \Pi^{n-1}$$

• Might not exist

• Might depend on P_1 choice of initial condition

• Ergodic Markov chain:

• P_∞ exists

• P_∞ independent of P_1

• $P_\infty = P^*$

Grünert
+
Stingaker
Secs 6.3
6.4

Proposition: If $(X_i)_{i=1}^n$ is an aperiodic and irreducible Markov chain, then $\lim_{n \rightarrow \infty} P_n = P^*$ for any P_1 .

Example: 2-state MC $1-\alpha \text{ } \textcircled{0} \xrightarrow{\alpha} \textcircled{1} \xrightarrow{1-\beta}$

$0 < \alpha, \beta < 1$: Ergodic $\bar{p}^* = \begin{pmatrix} \frac{\beta}{\alpha+\beta} & \frac{\alpha}{\alpha+\beta} \end{pmatrix}$

$\alpha = \beta = 0$: Not ergodic $\textcircled{0} \quad \textcircled{1}$
 Any P_i is stationary
 Reducible Markov chain

$\alpha = \beta = 1$: Not ergodic $\textcircled{0} \xrightarrow{1} \textcircled{1} \xrightarrow{1} \textcircled{0}$
 Periodic Markov chain

$$P_1 = \begin{pmatrix} a & b \end{pmatrix}$$

$$P_2 = \begin{pmatrix} b & a \end{pmatrix}$$

$$P_3 = \begin{pmatrix} a & b \end{pmatrix}$$

\vdots

$$P = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \end{pmatrix} \text{ stationary but not a limiting distribution}$$

• Ergodic theorem: If $(X_i)_{i=1}^n$ is an ergodic Markov chain, then

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n g(X_i) = E_{p^*}[g(X)] \quad \text{in probability}$$

estimate stationary expectation
time average γ
 $\hat{\delta}_n$ γ

$$\lim_{n \rightarrow \infty} P(|\hat{\delta}_n - \gamma| > \epsilon) = 0$$

• Generalization of law of large numbers (LLN) to Markov chains.

$$X_i \sim p^* \text{ iid} \qquad (X_i)_{i=1}^n \text{ MC} \\ \frac{1}{n} \sum_{i=1}^n g(X_i) \rightarrow E_{p^*}[g(X)] \text{ in prob.} \qquad \frac{1}{n} \sum_{i=1}^n g(X_i) \rightarrow E_{p^*}[g(X)] \text{ in prob.}$$

• Empirical occupation:

$$\hat{P}_n(j) = \frac{1}{n} \sum_{i=1}^n \delta_{X_i, j} = \text{fraction of time spent in } j$$

$$\delta_{i,j} = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$$

$$\hat{P}_n(j) \xrightarrow{n \rightarrow \infty} p^*(j) \quad \text{in prob.}$$

• Interpretations of p^* :

- 1- Distribution of X_n as $n \rightarrow \infty$
- 2- Long time (stationary) occupation

2.5. Stationary distribution

$$p^* = p^* \Pi$$

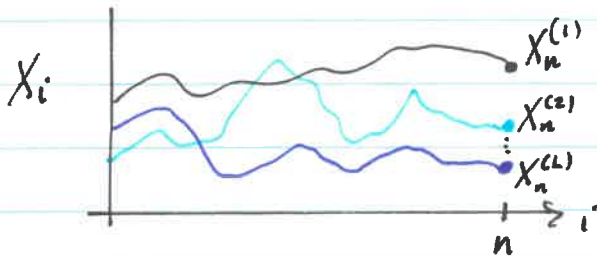
1- Direct calculation

- Input: Π
- Output: left eigenvector of Π with eigenvalue 1
- Normalization: $\sum_i p^*(i) = 1$

Code: `import scipy.linalg as la`
`pimat = np.array([[a, b, c], [...], [...]])`
`eigvals, eigvecs = la.eig(np.transpose(pimat))`

\uparrow $n \times n$ \uparrow why?

2- Parallel simulations



- Simulate L copies/realizations/trajectories

$$\left\{ \left(X_i^{(j)} \right)_{i=1}^n \right\}_{j=1}^L$$

$L =$ sample size / no. traj.
 $n =$ final time

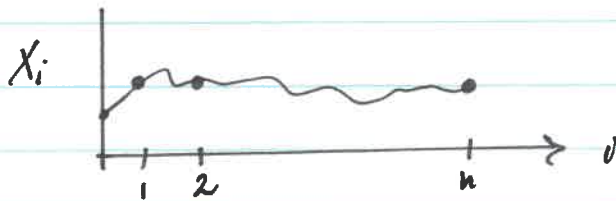
- Keep last state at time n : $\left\{ X_n^{(j)} \right\}_{j=1}^L$

- Histogram: $\hat{p}_{n,L}(i) \approx p_n(i)$ All final states (LLN)

- Convergence: $\hat{p}_{n,L}(i) \xrightarrow[n \rightarrow \infty]{L \rightarrow \infty} p^*(i)$

Code: $n = 100$
 $L = 10^{**5}$
 $x_sample = []$
 for $j = 1:L$
 $x = \text{initial value}$ \leftarrow deterministic or random
 for $i = 1:n$
 generate new x 2 loops
 append x to x_sample
 histogram(x_sample) $n \rightarrow \infty, L \rightarrow \infty$

3- Ergodic simulation



- Simulate 1 trajectory $(X_i)_{i=1}^n$
- Empirical occupation:

$$\hat{P}_n(j) = \frac{1}{n} \sum_{i=1}^n \delta_{X_i, j}$$

Histogram of all state in time

- Convergence: $\hat{P}_n(j) \xrightarrow{n \rightarrow \infty} P^*(j)$

Ergodic theorem

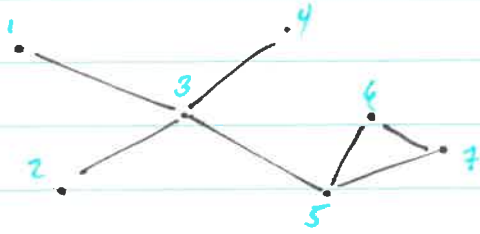
Code: $n = 10^{**3}$
 $x_sample = []$
 $x = \text{initial value}$ deterministic or random
 for $i = 1:n$
 generate new x 1 loop!
 append x to x_sample

histogram(x_sample)

$n \rightarrow \infty$

Trade off n vs $n \times L$

2.6. Application: Random walk on graphs



Graph: $G = (V, E)$

Undirected

Connected

vertices
nodes
edges

Adjacency matrix: $A_{ij} = \begin{cases} 1 & \text{if } i \sim j \\ 0 & \text{if } i \not\sim j \end{cases}$

connected

unconnected

$|V| \times |V|$ matrix

Symmetric $A = A^T$

$i \sim j \Rightarrow j \sim i$ reflexive

Node degree: $k_i = \# \text{ links to node } i$
 $= \sum_j A_{ij}$

Degree list: $\bar{k} = (k_1, k_2, k_3, \dots, k_{|V|})$

Number of edges: $M = \frac{1}{2} \sum_i k_i = \frac{1}{2} \sum_{ij} A_{ij}$

Uniform random walk (URW):

1- Start at node $X_i = i$

2- Choose node connected to i , random uniform
 k_i of them $\Rightarrow P(i \rightarrow j) = \frac{1}{k_i} \quad j \sim i$

3- Repeat

Transition matrix: $\Pi_{ij} = P(i \rightarrow j) = \frac{A_{ij}}{k_i}$

$0 \leq \Pi_{ij} \leq 1 \quad \forall i, j$

$\sum_j \Pi_{ij} = \frac{1}{k_i} \sum_j A_{ij} = 1 \quad \forall i$

Π ergodic if G connected

Stationary/ergodic distribution: $p^*(i) = \frac{k_i}{2M} \propto k_i$

Normalization: $\sum_i p^*(i) = \frac{1}{2M} \sum_i k_i = 1$

Occupation $p_n(i) \rightarrow p^*(i) \propto k_i$

Basis of Google PageRank

2.7. Metropolis-Hastings algorithm

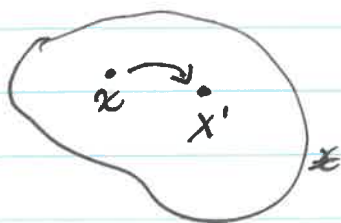
(1948) 2-11

lin
Chap. 5

- Refs:
 - Metropolis, Rosenbluth², Teller², 1953 $M(RT)^2$
 - Hastings 1970
- Top 10 algo of 20th century by SIAM

- Goal: Generate variates/values $X \sim f$ target distribution
 - $x \in \mathcal{X}$ state space \rightsquigarrow known, calculatable
 - $\sum_x f(x) = 1$

- Idea: Simulate ergodic Markov chain that has f as its stationary distribution.



Steps:

1- Initialize: $X_1 = x$ *deterministic or random*

2- Generate move/proposal:

$x \rightarrow x'$ with probability $q(x'|x)$

$$x' \sim q(\cdot | x)$$

3- Accept proposal with probability

$$\rho = \min \left\{ 1, \frac{q(x|x') f(x')}{q(x'|x) f(x)} \right\}$$

Metropolis-Hastings ratio

That is, $u \sim \mathcal{U}[0,1]$ *PMH*

if $u < \rho$ then

$$X_2 = x'$$

accept

else

$$X_2 = x$$

reject

4- Repeat

• Metropolis-Hastings MC:

$$\cdot \Pi(x'|x) = P(x \rightarrow x') = \begin{cases} \rho & x \neq x' \\ 1 - \rho & x' = x \end{cases}$$

• Ergodic MC

• Stationary distribution: $f(x)$ See CW2

• Remarks:

• Free to choose $q(x'|x)$

Possible moves

• Propose moves x' such that $f(x') > 0$

• $\text{supp}(f) \subseteq \bigcup_x \text{supp}(q(\cdot|x))$

• Move accepted for sure if $q(x|x')f(x') > q(x'|x)f(x)$
Move accepted with probability ρ otherwise

• Implementation: if $\rho_{MH} > 1$ or $u < \rho_{MH}$ then accept

check first

pares possibly generation of u

• Or: if $\log \rho_{MH} > 0$ or $\log u < \log \rho_{MH}$

• $f(x)$ needed only up to normalization factor: $f(x) = \alpha g(x)$

$$\Rightarrow \rho_{MH} = \frac{q(x|x')g(x')}{q(x'|x)g(x)}$$

• Choose q such that accepted fraction $\approx \frac{1}{2}$
acceptance ratio

Particular cases:

1- Independent random walk: $q(x'|x) = q(x')$

$$\Rightarrow p_{MH} = \frac{q(x) f(x')}{q(x') f(x)}$$

2- Metropolis algorithm: $q(x'|x) = q(x|x')$ symmetric

$$\Rightarrow p_M = \frac{f(x')}{f(x)} \quad \rho = \min \left\{ 1, \frac{f(x')}{f(x)} \right\}$$

- Accept move x' for sure if $f(x') \geq f(x)$
- Accept with prob. ρ if $f(x') < f(x)$

Reversible: $f(x) P(x \rightarrow x') = f(x') P(x' \rightarrow x)$ CW2
 high low low high

3- Metropolis random walk:

Move: $X' = X + \delta X$

Displacement: $\delta X \sim p$ symmetric

$$\Rightarrow q(x'|x) = q(x|x')$$

$$q(x'|x) = q(x \rightarrow x') = p(\delta x)$$

$$q(x|x') = q(x' \rightarrow x) = p(-\delta x)$$

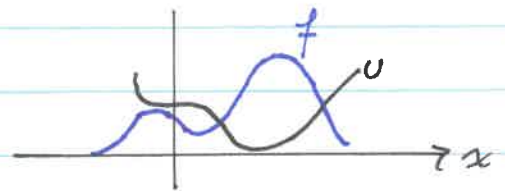
4- Heat bath algorithm:

Target: $f(x) = \frac{e^{-\beta U(x)}}{Z}$

$x \in \mathbb{R}^d$ or \mathbb{X}

$U: \mathbb{X} \rightarrow \mathbb{R}$ potential

$\beta \in \mathbb{R}$ usually $\beta > 0$ inverse temperature



$$\Rightarrow p_M = \frac{e^{-\beta U(x')}}{e^{-\beta U(x)}} = e^{-\beta \Delta U}$$

$$\Delta U = U(x') - U(x)$$

potential change

- ⇒
- Move accepted for sure if $\Delta U \leq 0$: $U(x') \leq U(x)$
 - " " with prob. p_M if $\Delta U > 0$: $U(x') > U(x)$
 - Potential minimization (not greedy)
 - Sample where $f(x)$ is large $\Leftrightarrow U(x)$ is low

• Example: $f \sim \mathcal{N}(\mu, \sigma^2)$

$$n = 10^{+3}$$

MC steps

$x_{\text{sample}} = []$

$x = \text{initial value}$

deterministic or random

for $i = 1:n$

disp $\sim \mathcal{U}[-a, a]$

Symmetric, $a = \text{size}$

$x_p = x + \text{disp}$

$p_M = f(x_p) / f(x)$

if $p_M > 1$ or $\text{rand}() < p_M$ then

$x = x_p$

accept
← no else

append x to x_{sample}

same x added / kept
if x_p not accepted

See demo

• MCMC optimization: $E_f[g(X)] = \gamma$

• Trajectory: $(X_i)_{i=1}^n$

• Estimator: $\hat{\gamma}_n = \frac{1}{n} \sum_{i=1}^n g(X_i)$

• Ergodic thm: $\hat{\gamma}_n \rightarrow \gamma$ in prob. as $n \rightarrow \infty$

• Comparison:

Standard MC

MCMC

- iid variates / samples
- No correlation
- Difficult in high dim
- Clever method needed

- MC variates
- Correlated samples
- Efficient in high dim
- Generic / "black box"

Bailer-Jones Chaps 8,9

2.8 MCMC inference

• Probabilistic model: $P(x|\theta)$ $x \in \mathcal{X}$ state
 $\theta \in \Omega$ parameter

• Parameter posterior:

$$P(\theta|D) = \frac{\overset{\text{likelihood}}{P(D|\theta)} \overset{\text{prior}}{P(\theta)}}{\underset{\text{data}}{P(D)} \underset{\text{evidence}}{P(D)}}$$

• likelihood: $P(D|\theta) = P(x_1, x_2, \dots, x_n | \theta)$
 $= \prod_i P(x_i | \theta)$ Naive Bayes

• Evidence:

$$P(D) = \int d\theta P(D|\theta) P(\theta)$$

• Tasks:

1- Parameter inference: See EW2

- $P(\theta|D)$ not known in closed form
 - Sample from $P(\theta|D)$
 - Propose move $\theta \rightarrow \theta'$
 - Accept with prob. $\rho = \min\left\{1, \frac{P(\theta'|D)}{P(\theta|D)}\right\}$ Under Metropolis
 - Data given
- $$= \min\left\{1, \frac{P(D|\theta')P(\theta')}{P(D|\theta)P(\theta)}\right\}$$
- No $P(D)$

2- Data generation

- Find best θ^* from D (e.g. most probable)
- Sample from $P(D|\theta^*)$
- Propose move $D \rightarrow D'$
- Used to complete missing data

3- Evidence calculation / model comparison

- Estimate integral $P(D) = \int d\theta P(D|\theta)P(\theta)$
- MC or MCMC

2.9. Error analysis

• Expectation: $\gamma = E_{\gamma}[g(X)]$ $X \sim f$ target distribution

• Estimator: $\hat{\gamma}_n = \frac{1}{n} \sum_{i=1}^n g(X_i)$ $(X_i)_{i=1}^n$ ergodic MC

• Error:

$$\hat{\gamma}_n \pm \sigma_n \quad \text{ci } 68\%$$

$$\hat{\gamma}_n \pm 2\sigma_n \quad \text{ci } 95\%$$

$$\sigma_n = \sigma(\hat{\gamma}_n) = \sqrt{\text{var}(\hat{\gamma}_n)}$$

$$\text{var}(\hat{\gamma}_n) \sim \frac{1}{n} \quad \text{but } \neq \frac{\sigma^2(g(X))}{n}$$

iid variance / naive variance

• Methods:

1- Independent simulations / runs

• Simulate L independent MCs: $\left\{ (X_i^{(j)})_{i=1}^n \right\}_{j=1}^L$

• Sample of estimators: $\left\{ \hat{\gamma}_n^{(j)} \right\}_{j=1}^L = S$

• Mean estimator: $\hat{\gamma}_{n,L} = \frac{1}{L} \sum_{j=1}^L \hat{\gamma}_n^{(j)}$

• Error: $\sigma_n = \sqrt{\text{var}(S)}$

• Variance: $\text{var}(S) = \frac{1}{L-1} \sum_{j=1}^L (\hat{\gamma}_n^{(j)} - \hat{\gamma}_{n,L})^2$

Standard iid variance

2- Ergodic simulation

• Simulate 1 trajectory: $(X_i)_{i=1}^n$

• Estimator: $\hat{\gamma}_n = \frac{1}{n} \sum_{i=1}^n g(X_i)$

• $\text{var}(\hat{\gamma}_n)$?

$$\begin{aligned} \text{var}(\hat{\delta}_n) &= \text{var}\left(\frac{1}{n} \sum_{i=1}^n g(X_i)\right) \\ &= \frac{1}{n^2} \text{var}\left(\sum_{i=1}^n g(X_i)\right) \neq \sum_i \text{var}(g(X_i)) \\ &= \frac{1}{n^2} \sum_{i,j=1}^n \text{cov}(g(X_i), g(X_j)) \end{aligned}$$

$$\begin{aligned} \text{cov}(X, Y) &= E[(X - E[X])(Y - E[Y])] && \text{Covariance} \\ \text{cov}(X, X) &= \text{var}(X) && \text{Variance} \end{aligned}$$

$$\begin{aligned} \text{var}(\hat{\delta}_n) &= \frac{1}{n^2} \left(\sum_{i=1}^n \text{var}(g(X_i)) + \sum_{i \neq j} \text{cov}(g(X_i), g(X_j)) \right) \\ &= \frac{1}{n^2} \left(\sum_{i=1}^n \text{var}(g(X_i)) + 2 \sum_{1 \leq j < k \leq n} \text{cov}(g(X_j), g(X_k)) \right) \end{aligned}$$

$(X_i)_{i=1}^n$ ergodic so $P_n(j) = P(X_n = j) \rightarrow f(j)$ as $n \rightarrow \infty$.

$$\Rightarrow \text{var}(\hat{\delta}_n) \sim \frac{1}{n^2} \left[\underbrace{n \text{var}_f(g(x))}_{\text{naive variance}} + 2n \sum_{k=1}^{\infty} \underbrace{\text{cov}_f(g(X_1), g(X_{1+k}))}_{\text{MC started at } f} \right]$$

$$= \frac{\text{var}_f(g(x))}{n} \left[1 + 2 \sum_{k=1}^{\infty} \text{corr}(g(X_1), g(X_{1+k})) \right]$$

$$\text{corr}(X, Y) = \frac{\text{cov}(X, Y)}{\sigma_X \sigma_Y} \quad \text{auto correlation} \quad \tau(g)$$

$$\Rightarrow \text{var}(\hat{\delta}_n) = \frac{\text{var}_f(g(x))}{n} \tau(g)$$

$$= \frac{\sigma_f^2(g(x))}{n_{\text{eff}}} \quad \text{naive variance}$$

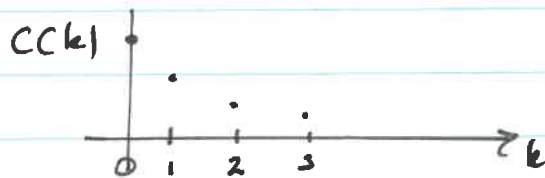
$$n_{\text{eff}} \sim \text{effective number of samples}$$

$$n_{\text{eff}} = \frac{n}{\tau(g)}$$

$\tau(g) \sim$ time scale of exponential decay of correlation

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• Example: $\text{corr}(g(X_1), g(X_{1+k})) = c(k) = \rho^k, \rho \in (0, 1)$

$$\Rightarrow 1 + 2 \sum_{k=1}^{\infty} c(k) = \frac{1+\rho}{1-\rho}$$



3- Batch means



- n samples
 - L batches/blocks of m points $L \times m = n$
 - Block average: $\hat{y}_j^m = \frac{1}{m} \sum_{j^{\text{th}} \text{ block}} g(X_k)$
 - Estimator: $\hat{\delta}_n = \frac{1}{L} \sum_{j=1}^L \hat{\delta}_j^m$
 - $n \rightarrow \infty, L \rightarrow \infty$ while $m \rightarrow \infty$, blocks become independent
- $$\Rightarrow \text{var}(\hat{\delta}_n) = \text{naive var}(\{\hat{\delta}_j^m\})$$